

17. Let  $\Pi$  be a plane and  $P(1, 2, 3)$  be a point not on  $\Pi$ .

Find the point  $Q$  on the plane  $\Pi$  such that the vector  $\overrightarrow{PQ}$  is orthogonal to  $\Pi$ .

18. Show that  $\mathbb{W} = \{(a, b, c, d) \in \mathbb{R}^4 : 2b + c = d \text{ and } a - b = 0\}$  is a subspace of  $\mathbb{R}^4$ .
19. Let  $\mathbb{V} = \{(x, y, z) : x, y, z \in \mathbb{R}\}$  and define  $(x, y, z) \oplus (a, b, c) = (x + a, y + b, z + c)$  and  $r \odot (x, y, z) = (rx, ry, 0)$ . Show that  $\mathbb{V}$  is not a vector space.
20. Determine whether  $\mathbb{W}$  is a subspace of  $\mathbb{R}^4$ :
- (a)  $\mathbb{W} = \{(x, y, z, w) : x + y + z + w = 0\}$ .
- (b)  $\mathbb{W} = \{(a, b, c, d) : ad - bc = 0\}$ .
21. Let  $\mathbf{X} = (1, 2, 3, 4)$  and  $\mathbf{Y} = (2, -1, -1, 0) \in \mathbb{R}^4$ . Show that  $\mathbf{Z} = (4, 3, 5, 8)$  belongs to  $\text{Span}\{\mathbf{X}, \mathbf{Y}\}$ .
22. Let  $\mathbb{W} = \{(a, b, c) \mid 2a + b = c\}$ . Show that  $\mathbb{W}$  is a subspace of  $\mathbb{R}^3$ .
23. Consider the set  $\mathbb{V} = \{(x, y, z) : x, y, z \in \mathbb{R}\}$  with the operations  $(x_1, y_1, z_1) \oplus (x_2, y_2, z_2) = (x_1 + x_2, y_1 + y_2, z_1 + z_2)$  and  $c \odot (x, y, z) = (z, y, x)$ . Is  $\mathbb{V}$  a vector space? Explain.
24. Determine whether  $\mathbb{W}$  is a subspace of  $\mathbb{R}^3$ :
- (a)  $\mathbb{W}_1 = \{(a, b, c) : (a + b)c = 0\}$ .
- (b)  $\mathbb{W}_2$  is the set of all vectors in  $\mathbb{R}^3$  which are orthogonal to  $\mathbf{X} = (1, -1, 2)$ .
25. Answer each question with "True" or "False" and justify your answer:
- (a) For a  $5 \times 5$  matrix  $A$ , the sign of the term  $a_{13}a_{21}a_{34}a_{45}a_{52}$  in  $\det(A)$  is "+".
- (b) If  $A$  is a non-singular  $3 \times 3$  matrix with  $\text{adj}(A) = -A$ , then  $|A| = -1$ .
- (c) There exist  $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^4$  such that  $\|\mathbf{X}\| = \|\mathbf{Y}\| = 2$  and  $\mathbf{X} \cdot \mathbf{Y} = 6$ .
- (d) In  $\mathbb{R}^3$ , if  $\mathbf{X} = 4\mathbf{Y}$ , then  $\mathbf{X} \times \mathbf{Y} = (0, 0, 0)$ .
- (e) The vector  $\mathbf{X} \times \mathbf{Y}$  is perpendicular to  $2\mathbf{X} + 3\mathbf{Y}$ .
- (f)  $\mathbb{V} = \{(x, y) \in \mathbb{R}^2 : y < 0\}$  is closed under the operation  $c \odot (x, y) = (cx, y)$ .
- (g) If  $A$  and  $B$  are two  $2 \times 2$  matrices such that  $|\text{adj}(A)| = |\text{adj}(B)|$ , then  $A = B$ .
- (h) In  $\mathbb{R}^3$ , the plane  $\Pi : y = 3$  is parallel to the  $y$ -axis.

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## 6.1 Real Vector Spaces

**Definition:** A real vector space  $\mathbb{V}$  is a set of elements with two operation  $\oplus$  and  $\odot$  satisfying the following conditions:

- ( $\alpha$ ) if  $x, y \in \mathbb{V}$ , then  $x \oplus y \in \mathbb{V}$ , that is  $\mathbb{V}$  is closed under  $\oplus$ .
- (a) for all  $x, y \in \mathbb{V}$ , we have  $x \oplus y = y \oplus x$ ,
- (b) for all  $x, y, z \in \mathbb{V}$ , we have  $x \oplus (y \oplus z) = (x \oplus y) \oplus z$ ,
- (c) for all  $x \in \mathbb{V}$ , there exists  $O \in \mathbb{V}$  such that  $x \oplus O = O \oplus x = x$ .
- (d) for each  $x \in \mathbb{V}$ , there is  $e \in \mathbb{V}$  such that  $e \oplus x = x \oplus e = O$ .
- ( $\beta$ ) if  $x \in \mathbb{V}$  and  $c \in \mathbb{R}$ , then  $c \odot x \in \mathbb{V}$ , that is  $\mathbb{V}$  is closed under  $\odot$ .
- (a) for all  $x, y \in \mathbb{V}$ , we have  $c \odot (x \oplus y) = c \odot x \oplus c \odot y$ , for all  $c \in \mathbb{R}$ ,
- (b) for all  $x \in \mathbb{V}$ , we have  $(c + d) \odot x = c \odot x \oplus d \odot x$  for all  $c, d \in \mathbb{R}$ ,
- (c) for all  $x \in \mathbb{V}$ , we have  $c \odot (d \odot x) = (cd) \odot x$  for all  $c, d \in \mathbb{R}$ ,
- (d) for all  $x \in \mathbb{V}$ , we have  $1 \odot x = x \odot 1 = x$ .

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## 6.2 Subspaces

**Definition:** Let  $(\mathbb{V}, \oplus, \odot)$  be a vector space, and let the non-empty set  $\mathbb{W} \subseteq \mathbb{V}$ . If  $(\mathbb{W}, \oplus, \odot)$  is also a vector space, then we say that  $\mathbb{W}$  is a **subspace** of  $\mathbb{V}$ .

**Theorem:** Let  $(\mathbb{V}, \oplus, \odot)$  be a vector space, and let  $\mathbb{W} \subseteq \mathbb{V}$ . Then,  $\mathbb{W}$  is a subspace of  $\mathbb{V}$  if and only if the following conditions hold:

1.  $\mathbb{W} \neq \emptyset$ ,
2. for all  $x, y \in \mathbb{W}$ , we have  $x \oplus y \in \mathbb{W}$ ,
3. for all  $x \in \mathbb{W}$  and  $c \in \mathbb{R}$ , we have  $c \odot x \in \mathbb{W}$ .

**Definition:** Let  $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_n$  be vectors in a vector space  $\mathbb{V}$ . A vector  $\mathbf{X} \in \mathbb{V}$  is called a **linear combination** of the vectors  $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_n$  if and only if

$$\mathbf{X} = c_1 \mathbf{X}_1 + c_2 \mathbf{X}_2 + \dots + c_n \mathbf{X}_n,$$

for some real numbers  $c_1, c_2, \dots, c_n$ .

**Definition:** Let  $S = \{\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_k\}$  be a subset of a vector space  $\mathbb{V}$ . Then, the set of all vectors in  $\mathbb{V}$  that are linear combination of the vectors of  $S$  is denoted by **span**  $S$  or **span**  $\{\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_k\}$ .

**Theorem:** Let  $S = \{\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_k\}$  be a set of vectors of a vector space  $\mathbb{V}$ , then **span**  $S$  is a subspace of  $\mathbb{V}$ .

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1. Let  $A = \begin{bmatrix} 1 & 1 & 1 & 2 & 3 \\ 4 & 6 & 0 & 0 & 0 \\ 3 & 5 & 3 & 6 & 9 \\ 2 & 3 & 2 & 4 & 6 \end{bmatrix}$ .

- (a) Find a basis for the row space of  $A$  that contains only rows of  $A$ .
- (b) Find a basis for the column space of  $A$ .
- (c) What is the nullity of  $A$ .

2. Let  $A = \begin{bmatrix} 1 & 2 & 2 & -1 \\ 3 & 6 & 5 & 0 \\ 2 & 4 & 2 & 4 \end{bmatrix}$ .

- (a) Find bases for the row space and the column space of  $A$ .
- (b) Find a basis for the null space of  $A$  ( i.e. the solution space of the system  $Ax = 0$ ).
- (c) What is the nullity and the rank of  $A$ .

3. Let  $A = \begin{bmatrix} 1 & 2 & 4 \\ 0 & -3 & 4 \\ 0 & -4 & 5 \end{bmatrix}$ . Determine whether the matrix  $A$  is diagonalizable. Justify your answer.

4. Let  $A = \begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$ .

- (a) Find the eigenvalues of  $A$ .
- (b) Find the corresponding eigenvectors of  $A$ .
- (c) If possible, find a non-singular matrix  $P$  and a diagonal matrix  $D$  such that  $D = P^{-1}AP$ .